

# **Fast Real-time Caustics from Height Fields**



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# Motivation

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- Caustics are important



no caustics



with caustics

# Motivation

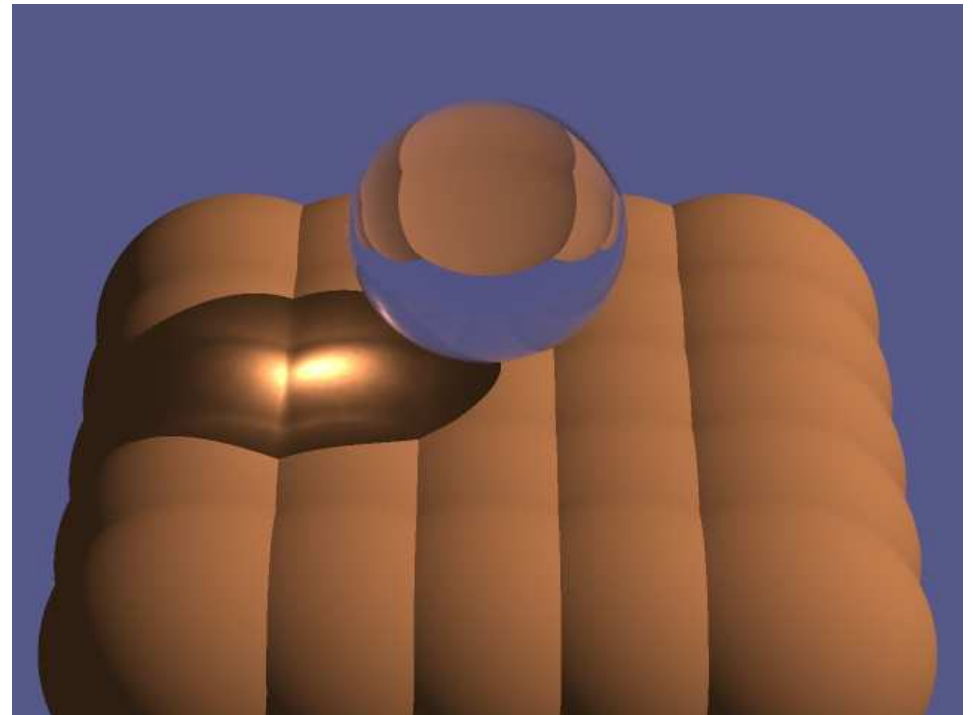
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- Caustics are important
- Caustics are SLOW!
- Current real-time systems
  - Fake caustics
  - No caustics
- Real-time caustics
  - Only in tech demos
- We need a FAST technique!

# Previous Work

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- ❑ Monte Carlo path tracing  
[Kajiya 1986]
- ❑ Wavefront propagation  
[Mitchell and Hanrahan 1992]
- ❑ Backward ray tracing  
[Arvo 1986]
- ❑ Photon mapping  
[Jensen 1996]



Photon mapping – Image courtesy of Henrik Wann Jensen

# Previous Work

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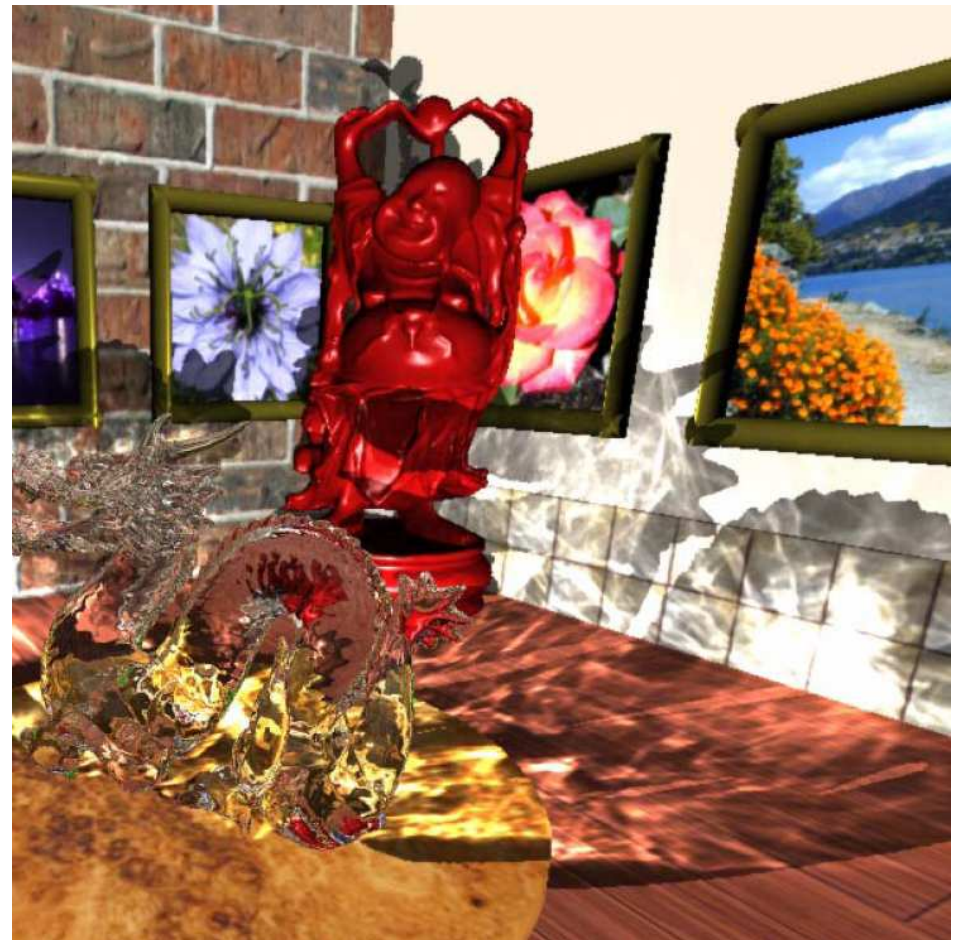
## □ Caustics maps

[Szirmay-Kalos et al. 2005]

[Wyman and Davis 2006]

[Shah et al. 2007]

[Wyman 2008]



Hierarchical caustic maps – Image courtesy of Chris Wyman



# Previous Work

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- Caustic textures

  - [Stam 1996]

- Beam Tracing

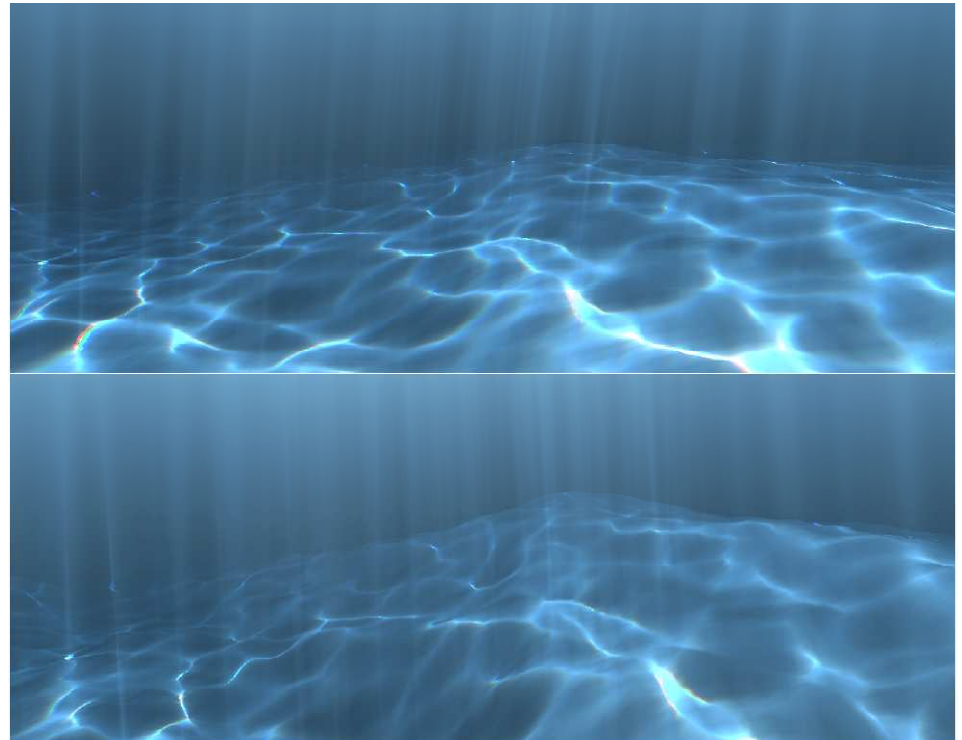
  - [Heckbert and Hanrahan 1984]

  - [Watt 1990]

  - [Nishita and Nakamae 1994]

  - [Iwasaki et al. 2001]

  - [Ernst et al. 2005]



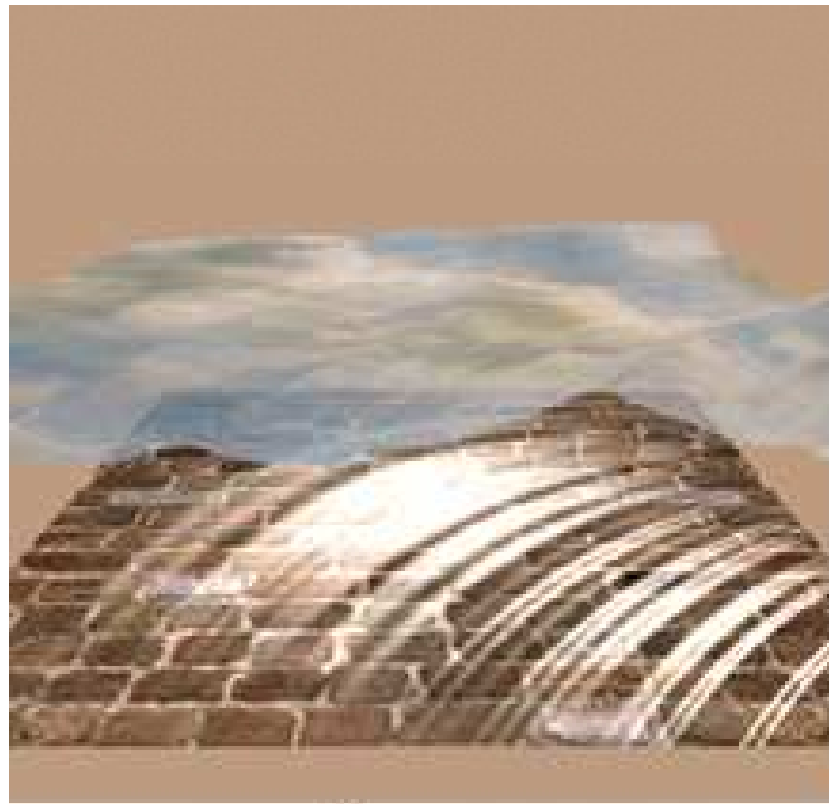
Interpolated Warped Volumes – Image courtesy of Ernst et al.



# Previous Work

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- Rendering Water Caustics – GPU Gems  
[Guardado and Sanchez-Crespo 2004]



Hierarchical caustic maps – Image courtesy of Guardado and Sanchez-Crespo

# Our Solution

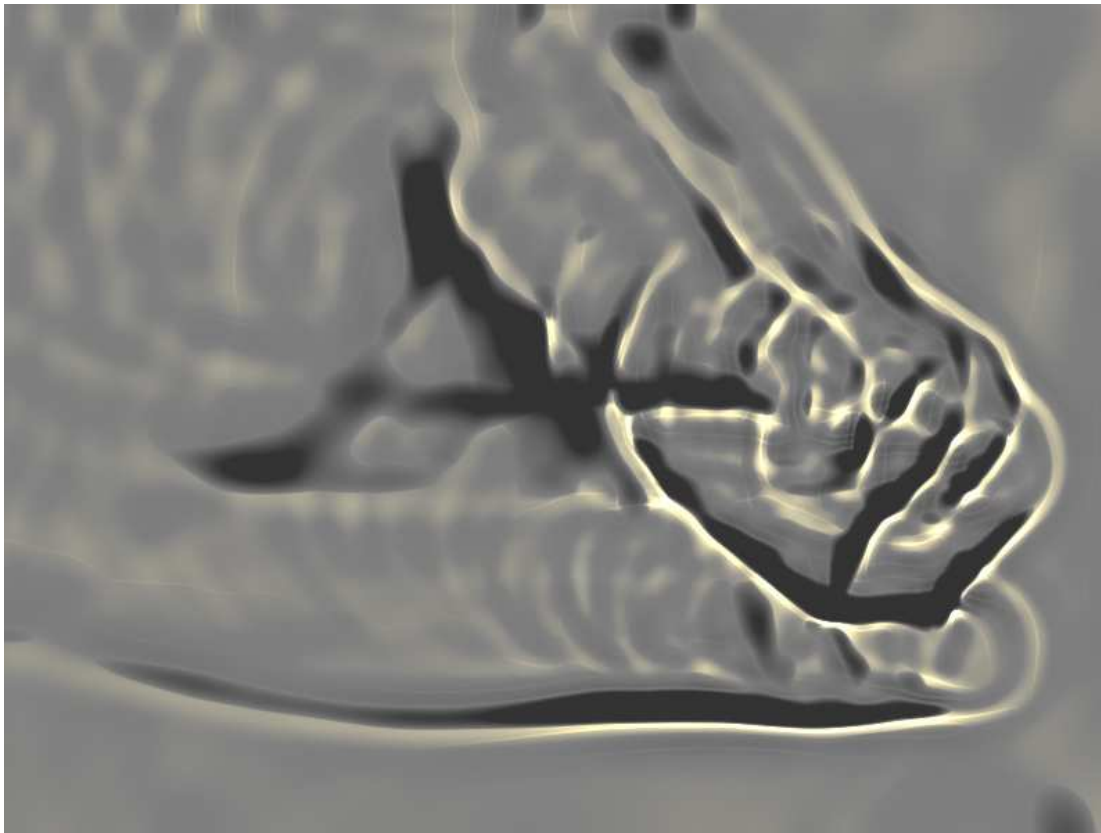
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- ❑ Fast real-time caustics
- ❑ From a height field surface
- ❑ Onto a planar surface

# Caustics Computation

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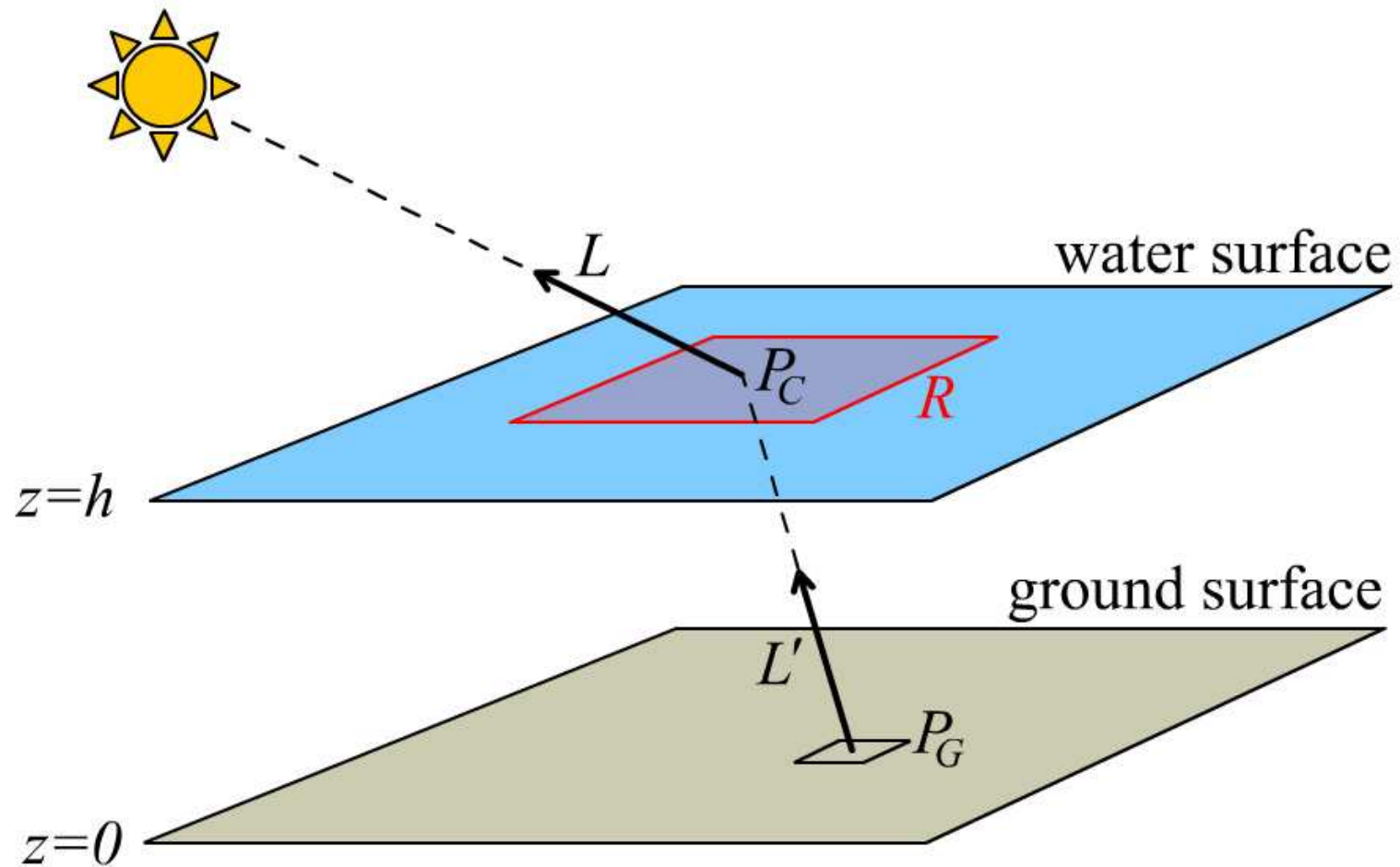
- Starting from the caustic-receiving surface
  - Flat plane
  - A caustic map that is mapped onto this plane





# Caustics Computation

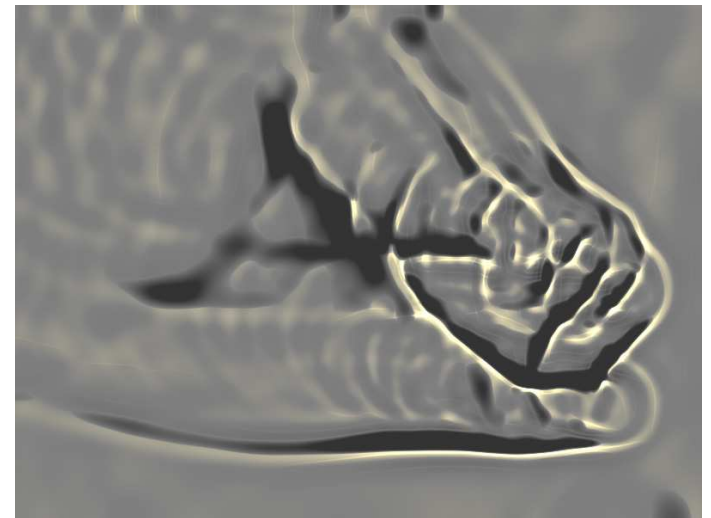
- For each pixel, sum refracted radiances toward the pixel



# Caustics Computation

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- Accurate as long as  $R$  is large enough
- Less accurate when the height field has
  - Large and
  - High frequency deformations
- Too small  $R \rightarrow$  Underestimation
- Most simulations require very small  $R$



# The Two-Pass Algorithm

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- Similar to separable convolution filtering
- Pass 1: caustics in X direction
- Pass 2: caustics in Y direction

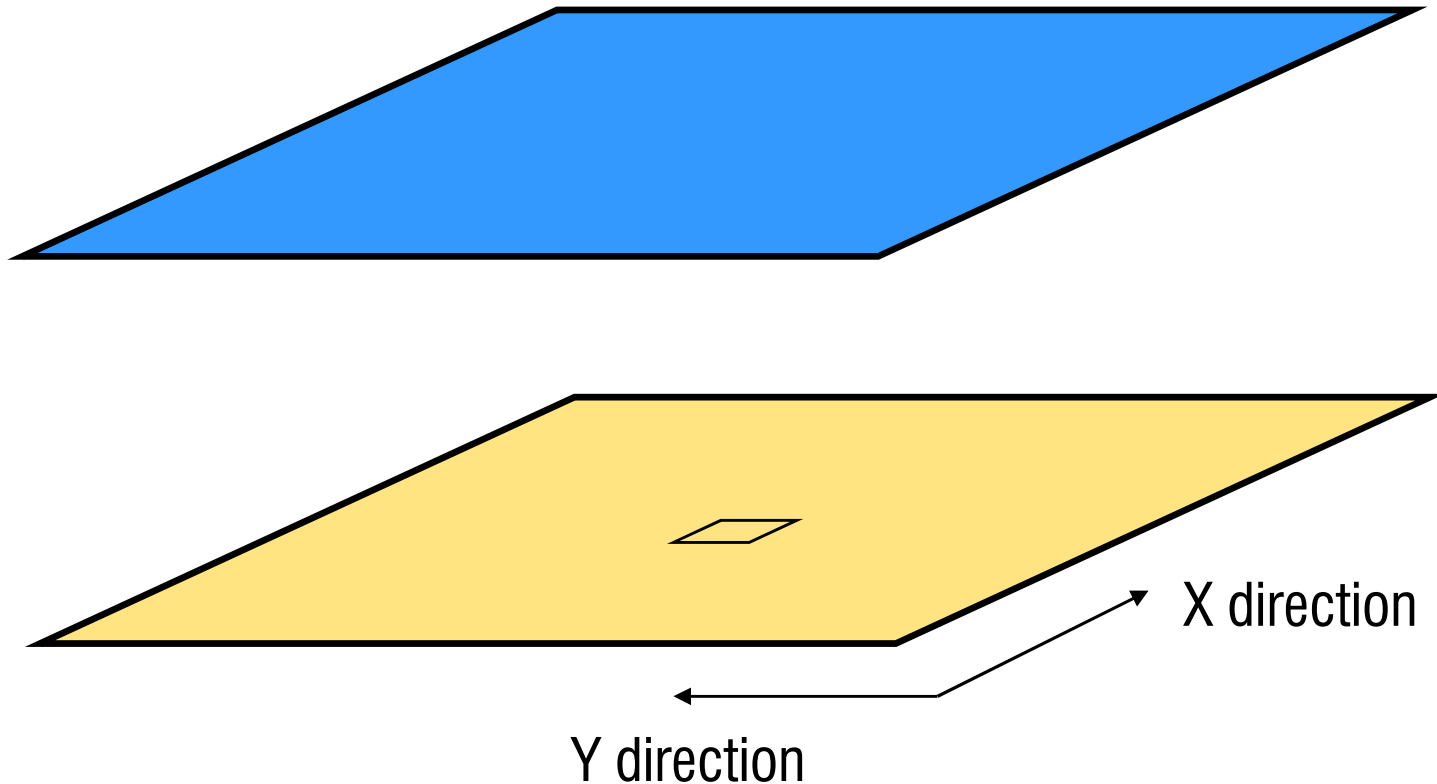
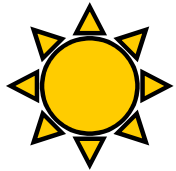




# The Two-Pass Algorithm

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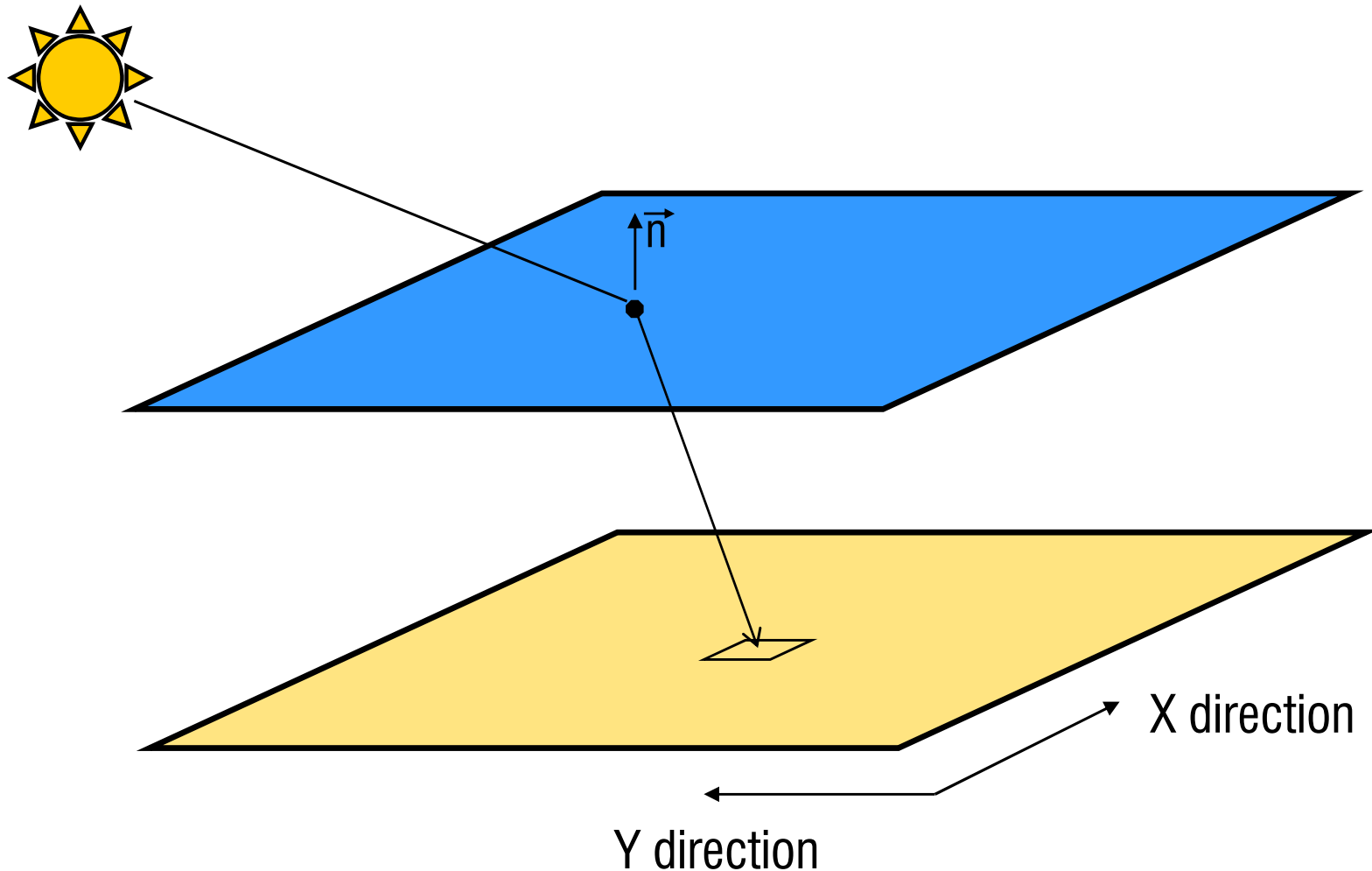
□ Pass 1:



# The Two-Pass Algorithm

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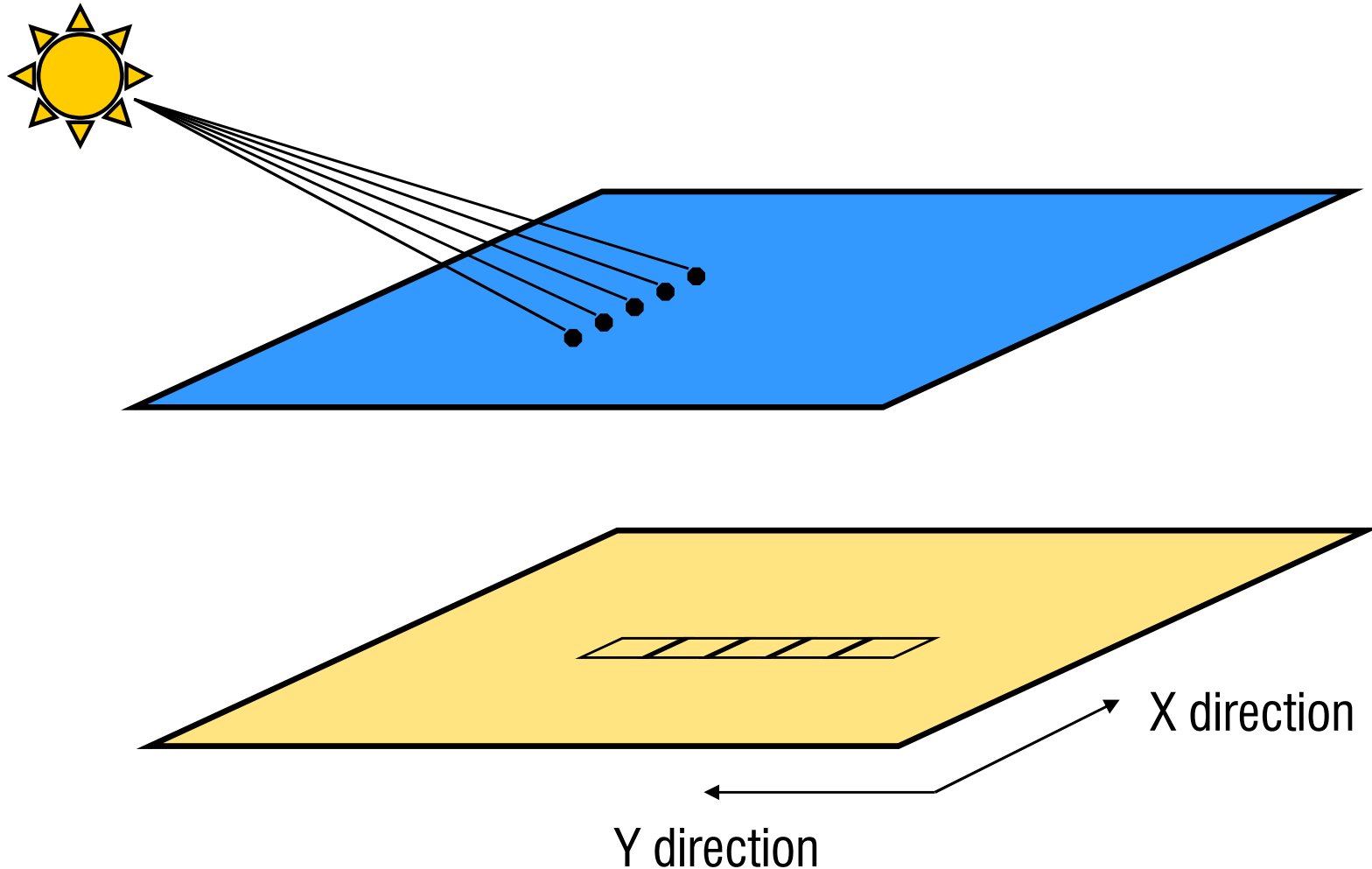
## □ Pass 1:



# The Two-Pass Algorithm

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## □ Pass 1:

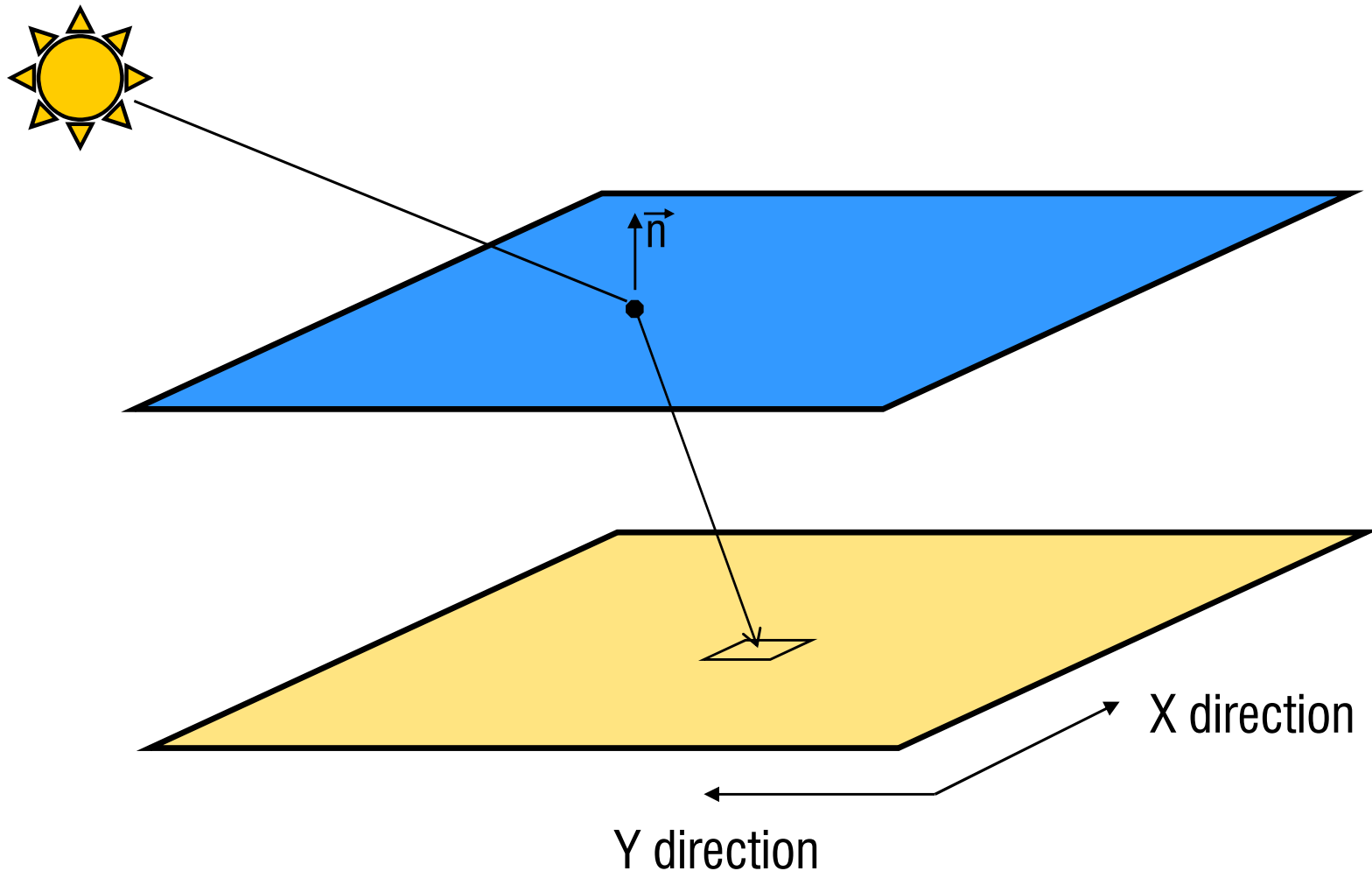




# The Two-Pass Algorithm

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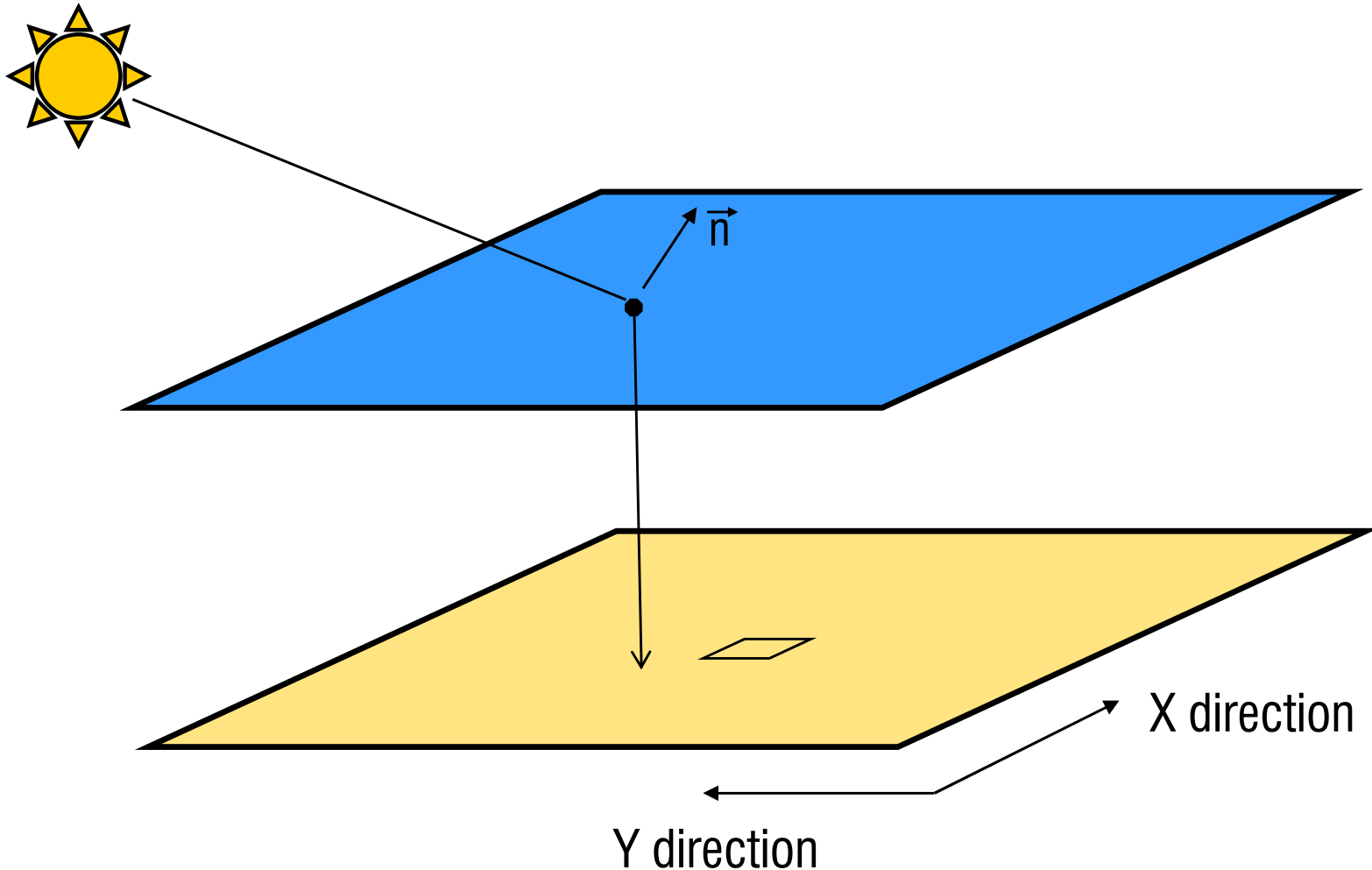
## □ Pass 1:



# The Two-Pass Algorithm

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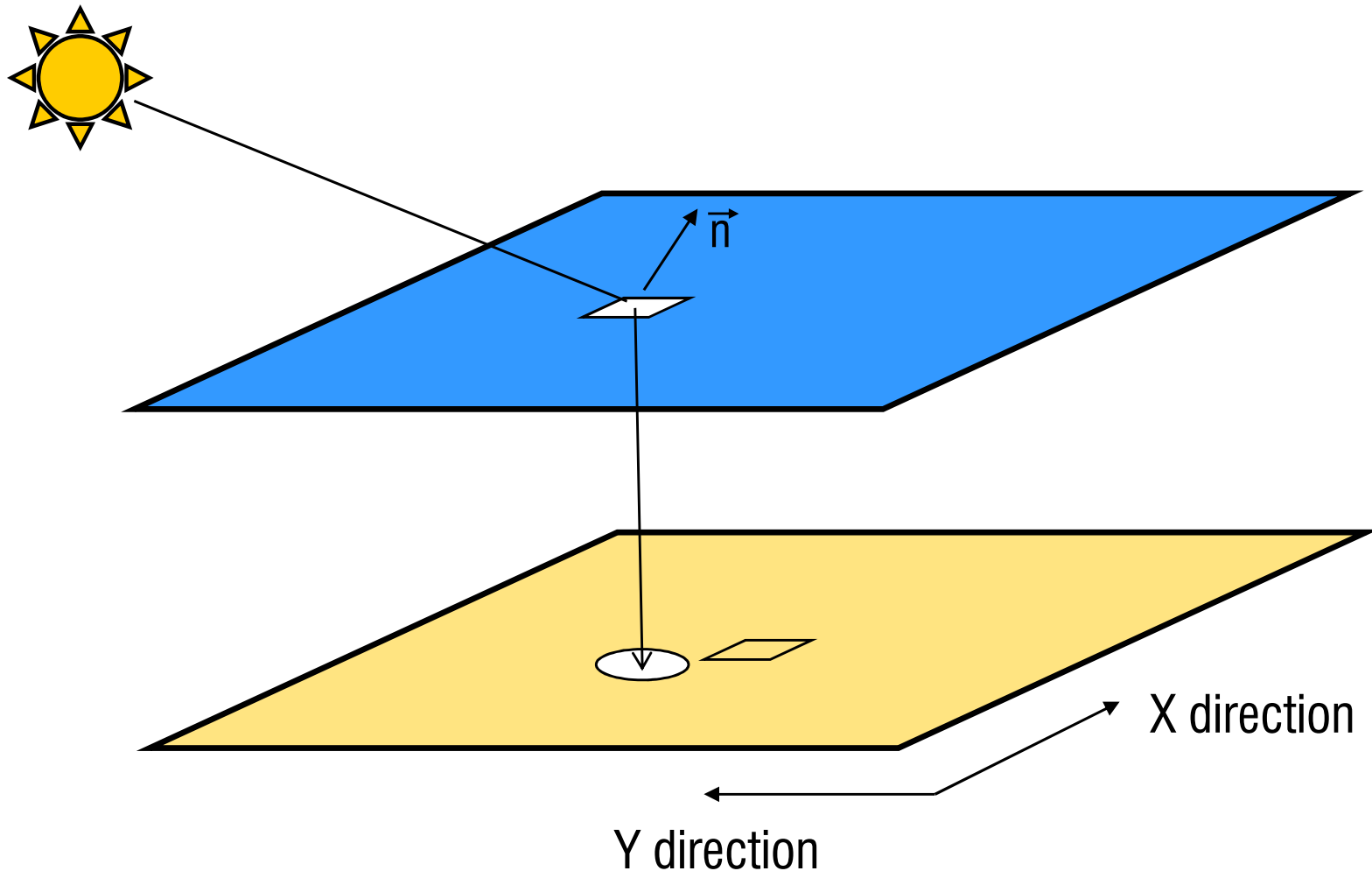
## □ Pass 1:



# The Two-Pass Algorithm

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## □ Pass 1:

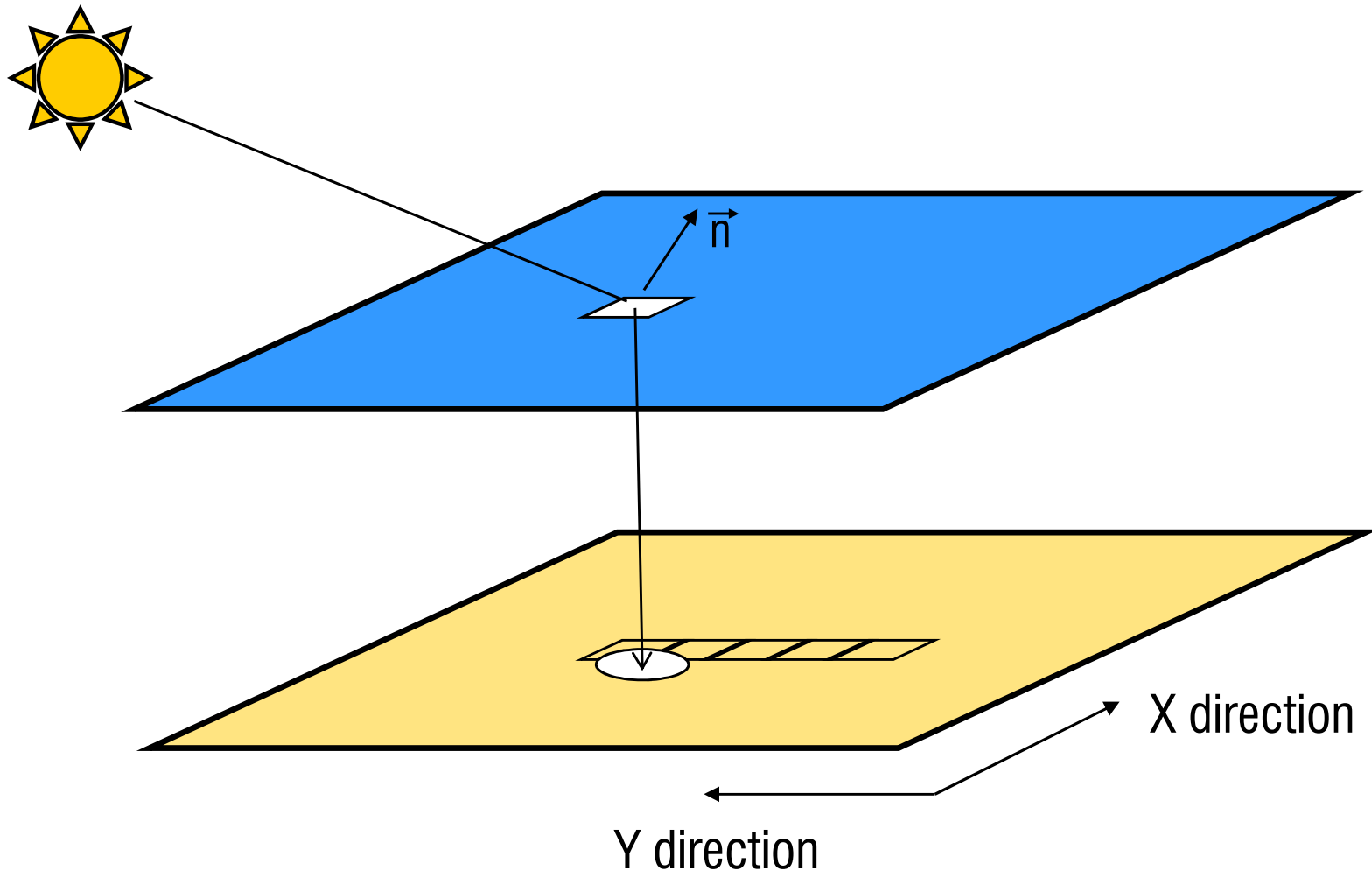




# The Two-Pass Algorithm

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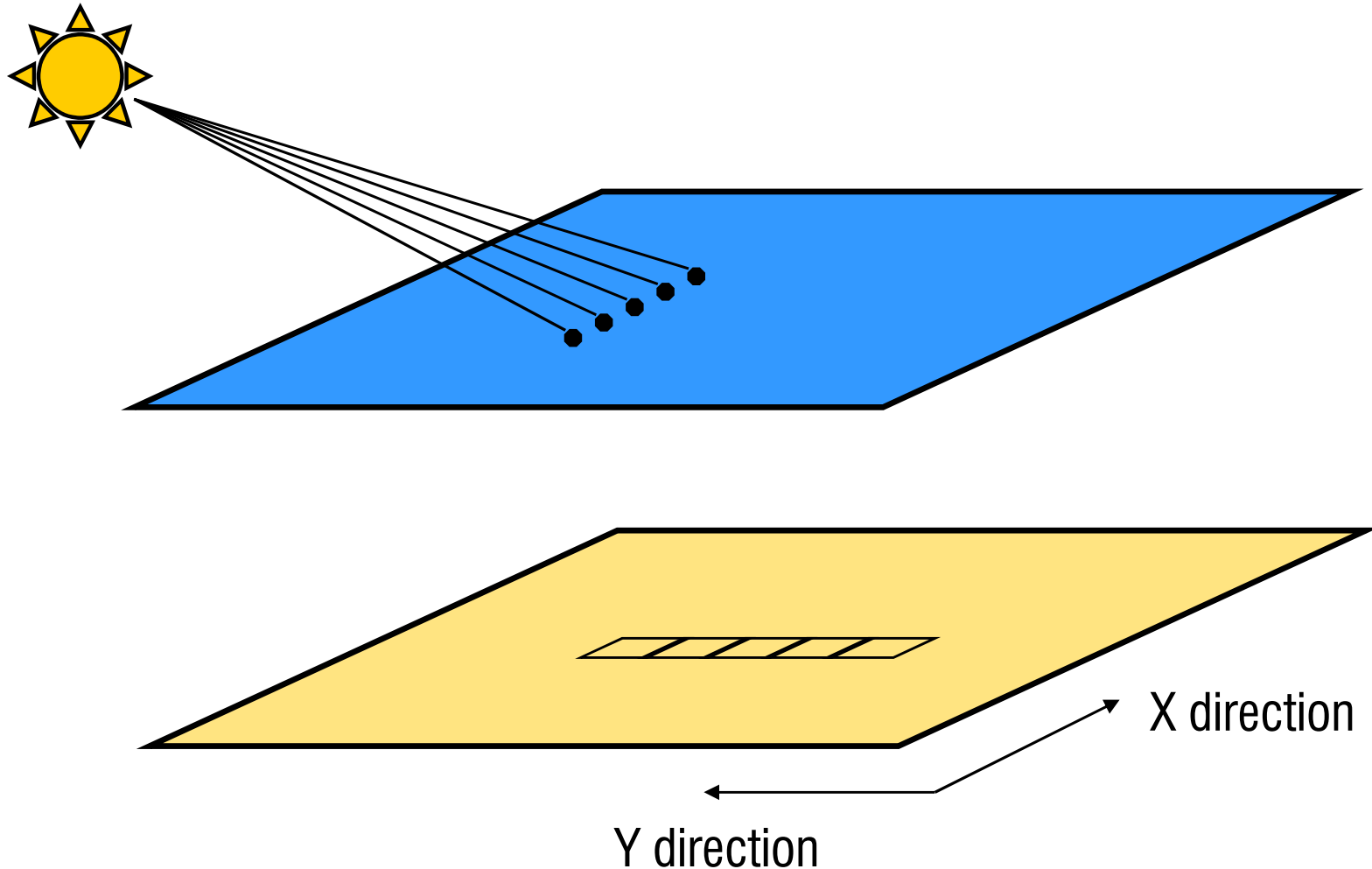
## □ Pass 1:



# The Two-Pass Algorithm

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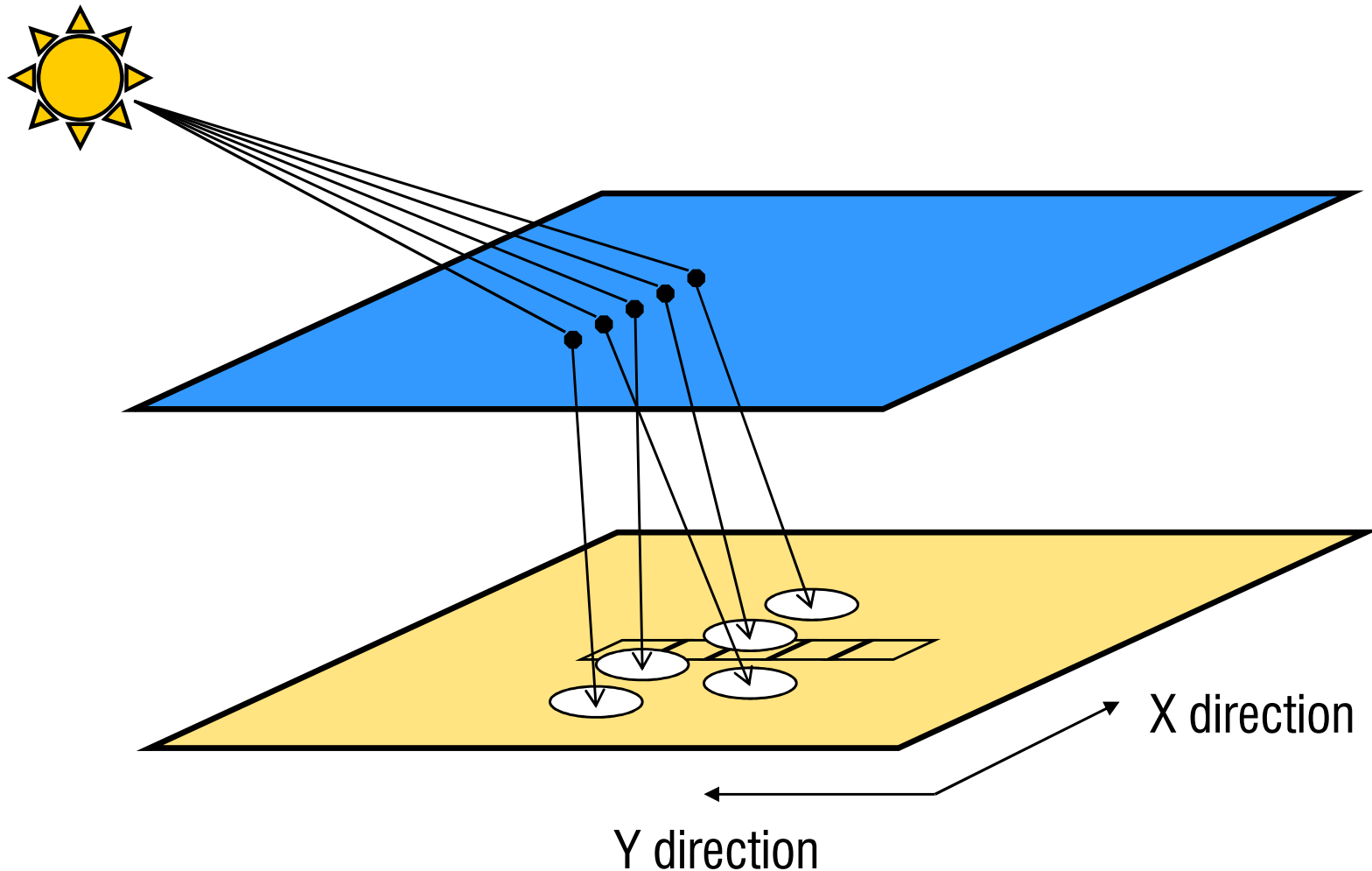
## □ Pass 1:



# The Two-Pass Algorithm

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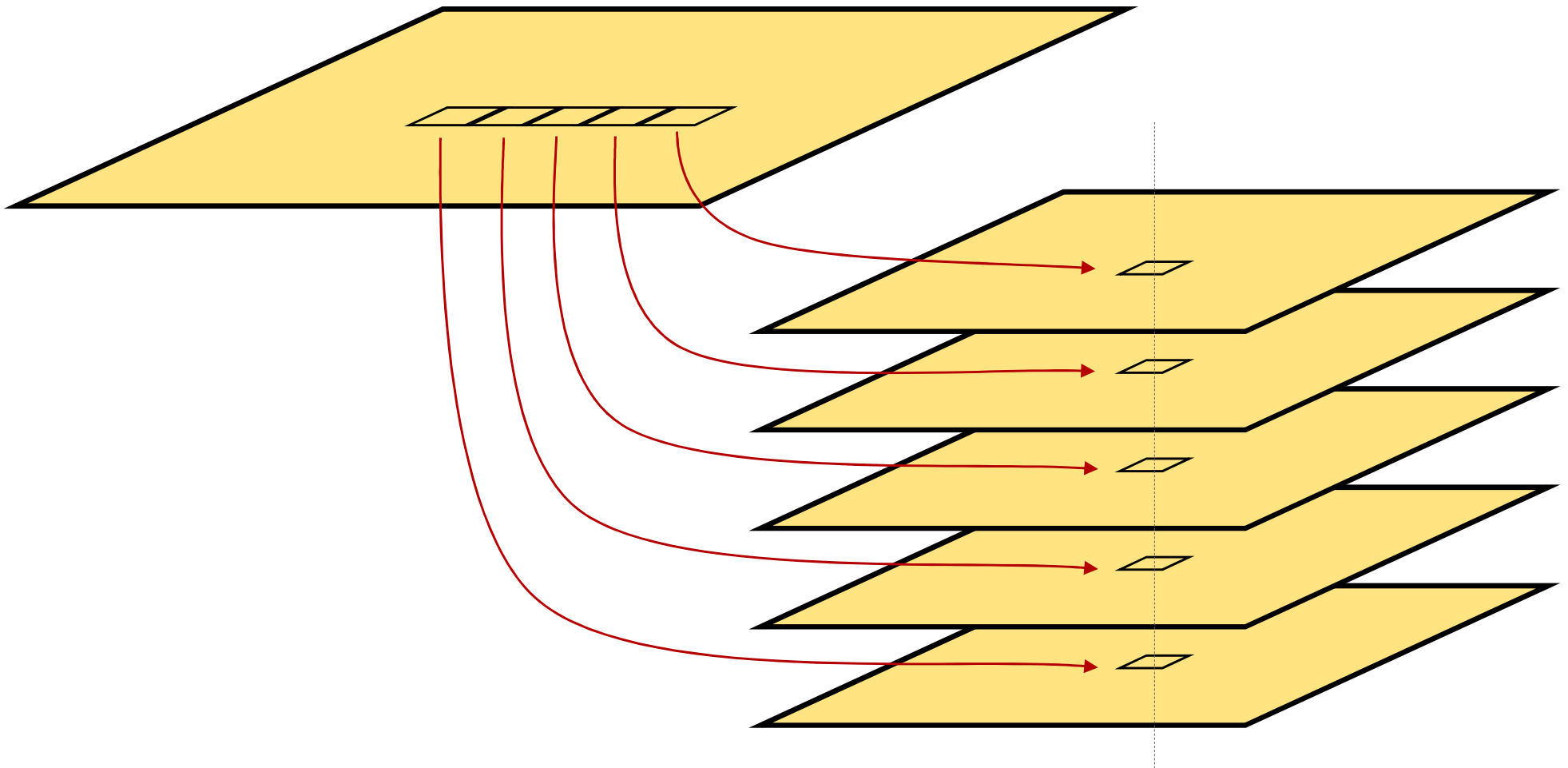
## □ Pass 1:



# The Two-Pass Algorithm

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□ Pass 1:

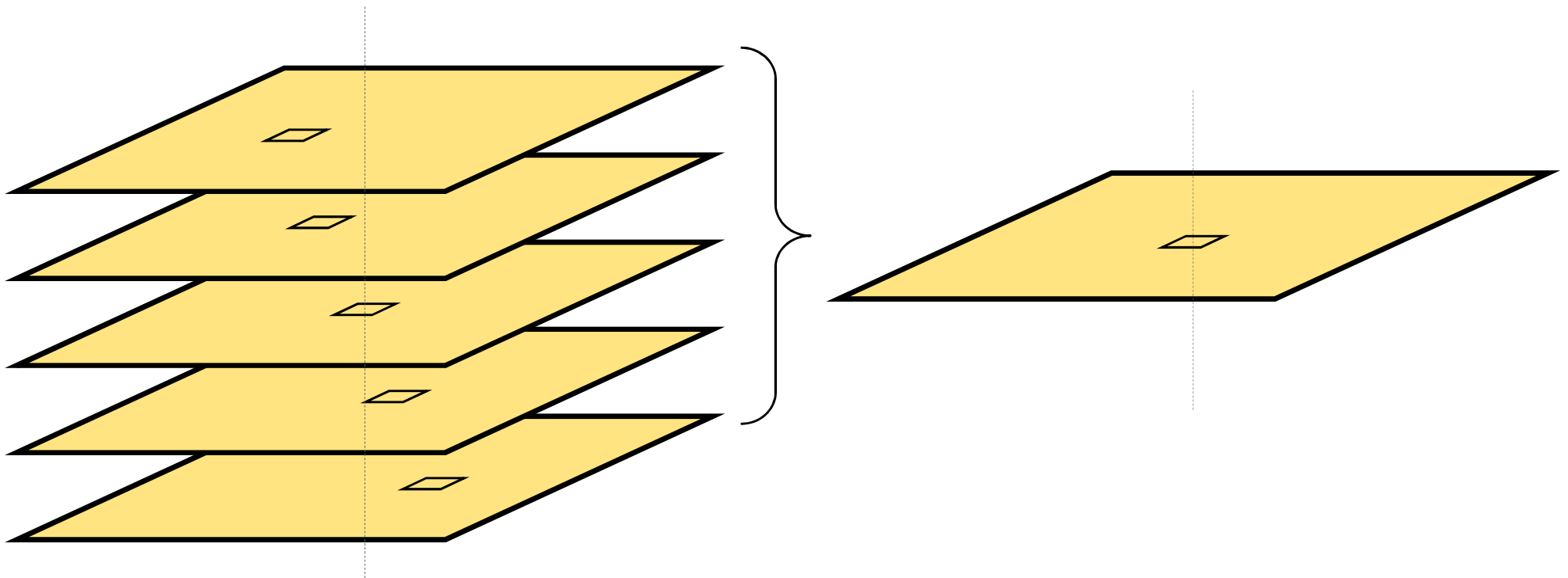




# The Two-Pass Algorithm

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- Pass 2:
  - Accumulate caustic values at different textures



# Implementation

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- The whole computation is in Fragment Shaders
- Repeated computations in Pass 1
  - Refracted ray directions
- Speed-up
  - Introduce an additional pass before Pass 1
  - Precompute refracted ray directions
- Pseudo codes for Pass 1 and Pass 2 are in the paper.

# Implementation

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```
void Pass1( out Pass1Out Out,
           in float2 P_G : TEXCOORD0,
           in float2 P_C : TEXCOORD1,
           uniform sampler2D heightField )
{
    // initialize output intensities
    float intensity[N];
    for ( int i=0; i<N; i++ ) intensity[i] = 0;
    // initialize caustic-receiving pixel positions
    float P_Gy[N];
    for ( int i=-N_HALF; i<=N_HALF; i++ ) P_Gy[i] = P_G.y + i;
    // for each sample on the height field
    for ( int i=0; i<N; i++ ) {
        // find the intersection with the ground plane
        float3 pN = P_C + ( i - N_HALF ) * xDirection;
        float2 intersection = GetIntersection( heightField, pN );
        // ax is the overlapping distance along x-direction
        float ax = max(0, 1 - abs(P_G.x - intersection.x));
        // for each caustic-receiving pixel position
        for ( int j=0; j<N; j++ ) {
            // ay is the overlapping distance along y-direction
            float ay = max(0, 1 - abs(P_Gy[j] - intersection.y));
            // increase the intensity by the overlapping area
            intensity[j] += ax*ay;
        }
    }
    // copy the output intensities to the color channels
    Out.color0 = float4( intensity[0], intensity[1], intensity[2], intensity[3] );
    Out.color1 = float3( intensity[4], intensity[5], intensity[6] );
}
```

# Implementation

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```
void Pass2( out float4 color : COLOR,
            in float2 P_G : TEXCOORD0,
            uniform sampler2D inColor0,
            uniform sampler2D inColor1 )
{
    float val = 0;
    val += tex2D( inColor0, P_G + float2( 0, -3 ) ).r;
    val += tex2D( inColor0, P_G + float2( 0, -2 ) ).g;
    val += tex2D( inColor0, P_G + float2( 0, -1 ) ).b;
    val += tex2D( inColor0, P_G ).a;
    val += tex2D( inColor1, P_G + float2( 0, 1 ) ).r;
    val += tex2D( inColor1, P_G + float2( 0, 2 ) ).g;
    val += tex2D( inColor1, P_G + float2( 0, 3 ) ).b;
    color = val;
}
```

# Results

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# Final Points

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## □ Advantages

- Works fast!
- Does not require high-res water surface
- Sequential texture access – cache friendly

## □ Limitations

- Water surface must be a height field
- Receiving surface must be a plane
- Underestimation when  $R$  is too small

## □ Non-planar receivers?

- Can be approximated as planar
- Better than no caustics or “fake” caustics



# Questions?

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no caustics



with caustics